



(Use as many sheets as necessary)

Sheet	1	of	2
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Application Number	10/616,096
Filing Date	July 8, 2003
First Named Inventor	Oleynikov et al.
Art Unit	2837
Examiner Name	Unknown
Attorney Docket Number	UNMC/0006

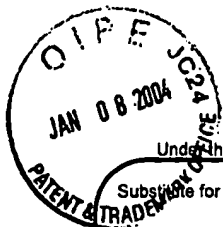
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INFORMATION DISCLOSURE STATEMENT BY APPLICANT (Use as many sheets as necessary)		Complete if Known			
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Sheet	2	of	2	Attorney Docket Number	UNMC/0006

NON PATENT LITERATURE DOCUMENTS			
Examiner Initials*	Cite No. ¹	Include name of the author (in CAPITAL LETTERS), title of the article (when appropriate), title of the item (book, magazine, journal, serial, symposium, catalog, etc.), date, page(s), volume-issue number(s), publisher, city and/or country where published.	T ²
JP	1	Fireman, Z. et al. "Diagnosing small bowel Crohn's disease with wireless capsule endoscopy." <u>Gut Online</u> . 2003, 52: 390-392. BMJ Publishing Group Ltd.	
JP	2	Abbou, Clement-Claude et al. "Laparoscopic Radical Prostatectomy with a Remote Controlled Robot." <u>The Journal of Urology</u> . June 2001, 165: 1964-1966.	
JP	3	Fraulob, S. et al. "Miniature assistance module for robot-assisted heart surgery." <u>Biomed. Tech.</u> 2002, 47 Suppl. 1, Pt. 1: 12-5.	✓
	4	Guber, A. E. et al. "Miniaturized Instrument Systems for Minimally Invasive Diagnosis and Therapy." <u>Biomedizinische Technik</u> . 2002, Band 47, Ergänzungsband 1: 198-201.	✓

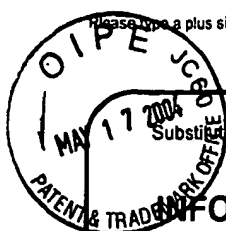
English
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Examiner Signature	<i>Paul JP</i>	Date Considered	<i>8/25/04</i>
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**INFORMATION DISCLOSURE
STATEMENT BY APPLICANT**

(Use as many sheets as necessary)

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of 1

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First Named Inventor	Oleynikov et al.
Group Art Unit	2837
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Attorney Docket Number	UNMC/0006
Submission Date	5/13/04

NON PATENT LITERATURE DOCUMENTS

Examiner Initials*	Cite No. ¹	Include name of the author (in CAPITAL LETTERS), title of the article (when appropriate), title of the item (book, magazine, journal, serial, symposium, catalog, etc.), date, page(s), volume-issue number(s), publisher, city and/or country where published	T ²
gp	1	Thomann, G. et al. "The Design of a new type of Micro Robot for the Intestinal Inspection." <u>Proceedings of the 2002 IEEE/RSJ Intl. Conference on Intelligent Robots and Systems EPFL</u> . October 2002: 1385-1390.	
gp	2	Guo, Shuxiang et al. "Fish-like Underwater Microrobot with 3 DOF." <u>Proceedings of the 2002 IEEE International Conference on Robotics & Automation</u> . May 2002: 738-743.	
gp	3	Fukuda, Toshio et al. "Mechanism and Swimming Experiment of Micro Mobile Robot in Water." <u>Proceedings of the 1994 IEEE International Conference on Robotics and Automation</u> . 1994: 814-819.	
gp	4	Guo, Shuxiang et al. "Micro Active Guide Wire Catheter System-Characteristic Evaluation, Electrical Model and Operability Evaluation of Micro Active Catheter." <u>Proceedings of the 1996 IEEE International Conference on Robotics and Automation</u> . April 1996: 2226-2231.	
gp	5	Yu, Sun et al. "Microrobotic Cell Injection." <u>Proceedings of the 2001 IEEE International Conference on Robotics & Automation</u> . May 2001: 620-625.	
gp	6	Ruurda, JP et al. "Robot-assisted surgical systems: a new era in laparoscopic surgery." <u>Ann. R. Coll. Surg. Engl.</u> 2002, 84: 223-226.	
gp	7	Menciassi, A. et al. "Robotic Solutions and Mechanisms for a Semi-Autonomous Endoscope." <u>Proceedings of the 2002 IEEE/RSJ Intl. Conference on Intelligent Robots and Systems EPFL</u> . October 2002: 1379-1384.	
gp	8	Ishiyama, K. et al. "Spiral-type Micro-machine for Medical Applications." <u>2000 International Symposium on Micromechatronics and Human Science</u> . 2000: 65-69.	
gp	9	Fearing, R. S. et al. "Wing Transmission for a Micromechanical Flying Insect." <u>Proceedings of the 2000 IEEE International Conference on Robotics & Automation</u> . April 2000: 1509-1516.	
gp	10	Mei, Tao et al. "Wireless Drive and Control of a Swimming Microrobot." <u>Proceedings of the 2002 IEEE International Conference on Robotics & Automation</u> . May 2002: 1131-1136.	

Examiner

Paul gp

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